

Introduction  
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ADMM  
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Differential Privacy  
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Recycled ADMM  
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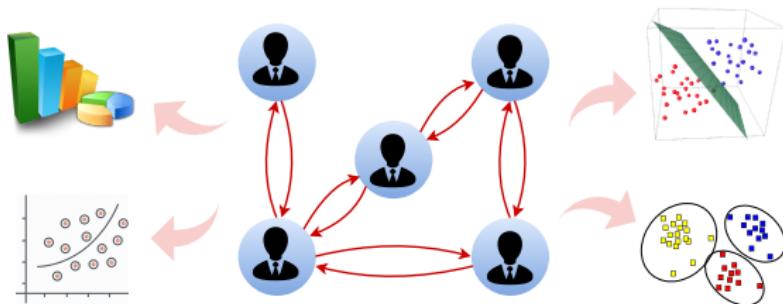
Results  
ooooo

# Recycled ADMM: Improve Privacy and Accuracy with Less Computation in Distributed Algorithms

**Xueru Zhang, Mohammad Mahdi Khalili, Mingyan Liu**

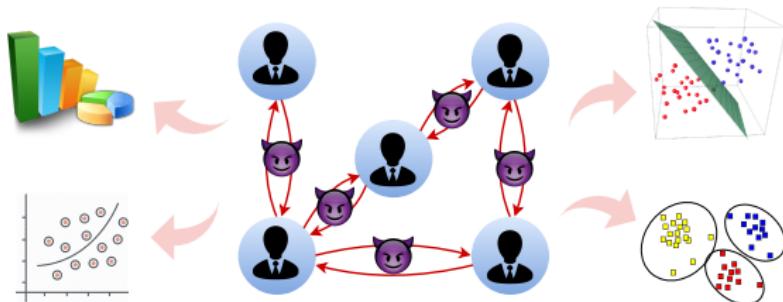
EECS Department, University of Michigan, Ann Arbor

# Motivation



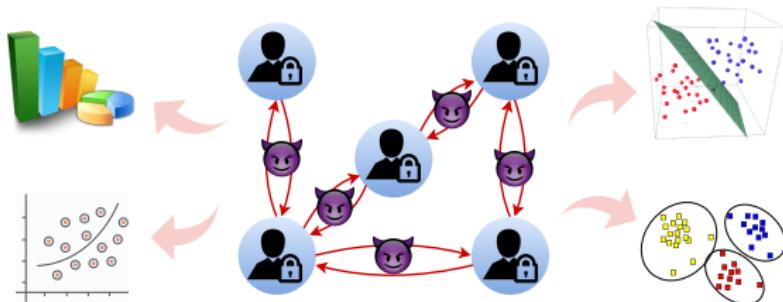
- Need to perform distributed learning tasks.
  - Data may have different owners, locality, etc.
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  - Common computational objective.
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*How to accomplish the computational tasks without jeopardizing privacy?*

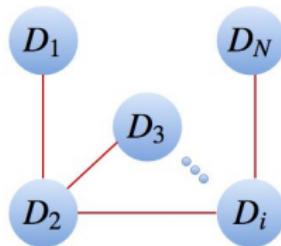
# Problem Formulation

- Regularized Empirical Risk Minimization

$$\min_{f_c} O_{ERM}(f_c, \{D_i\}_{i=1}^N) = \sum_{i=1}^N O(f_c, D_i)$$

where

$$O(f_c, D_i) = \frac{C}{B_i} \sum_{n=1}^{B_i} \mathcal{L}(y_i^n f_c^T x_i^n) + \frac{\rho}{N} R(f_c)$$



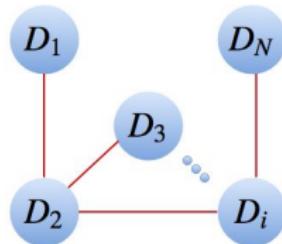
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- Distributed optimization
  - (Sub)gradient based
  - Alternating Direction Method of Multipliers (ADMM) based

## Conventional ADMM

- Introduce local variables and auxiliary variables to decentralize:

$$\begin{aligned} \min_{\{\mathbf{f}_i\}, \{\mathbf{w}_{ij}\}} \quad & \tilde{O}_{ERM}(\{\mathbf{f}_i\}_{i=1}^N, D_{all}) = \sum_{i=1}^N O(\mathbf{f}_i, D_i) \\ \text{s.t.} \quad & \mathbf{f}_i = \mathbf{w}_{ij}, \quad \mathbf{w}_{ij} = \mathbf{f}_j, \quad i \in \mathcal{N}, j \in \mathcal{V}_i \end{aligned}$$

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s.t.  $\mathbf{f}_i = \mathbf{w}_{ij}, \mathbf{w}_{ij} = \mathbf{f}_j, \quad i \in \mathcal{N}, j \in \mathcal{V}_i$

- Dual variables:  $\lambda_{ij}^a \sim (f_i = w_{ij}), \lambda_{ij}^b \sim (w_{ij} = f_j)$ .

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- Augmented Lagrangian:

$$\begin{aligned} L_\eta(\{f_i\}, \{w_{ij}, \lambda_{ij}^k\}) &= \sum_{i=1}^N O(f_i, D_i) + \sum_{i=1}^N \sum_{j \in \mathcal{V}_i} (\lambda_{ij}^a)^T (f_i - w_{ij}) \\ &\quad + \sum_{i=1}^N \sum_{j \in \mathcal{V}_i} (\lambda_{ij}^b)^T (w_{ij} - f_j) \\ &\quad + \sum_{i=1}^N \sum_{j \in \mathcal{V}_i} \frac{\eta}{2} (\|f_i - w_{ij}\|_2^2 + \|w_{ij} - f_j\|_2^2) \end{aligned}$$

# Conventional ADMM

In the  $(t + 1)$ -th iteration, the ADMM updates consist of the following:

primal updates:

$$f_i(t + 1) = \underset{f_i}{\operatorname{argmin}} L_\eta(\{f_i\}, \{w_{ij}(t), \lambda_{ij}^k(t)\}) ;$$

$$w_{ij}(t + 1) = \underset{w_{ij}}{\operatorname{argmin}} L_\eta(\{f_i(t + 1)\}, \{w_{ij}, \lambda_{ij}^k(t)\}) ;$$

dual updates:

$$\lambda_{ij}^a(t + 1) = \lambda_{ij}^a(t) + \eta(f_i(t + 1) - w_{ij}(t + 1)) ;$$

$$\lambda_{ij}^b(t + 1) = \lambda_{ij}^b(t) + \eta(w_{ij}(t + 1) - f_j(t + 1)) .$$

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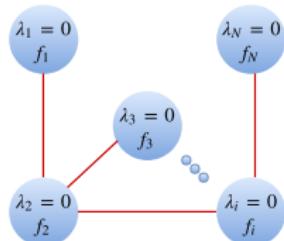
$$\begin{aligned} f_i(t+1) &= \underset{f_i}{\operatorname{argmin}} \{ O(f_i, D_i) + 2\lambda_i(t)^T f_i \\ &\quad + \eta \sum_{j \in \mathcal{V}_i} \left\| \frac{1}{2}(f_i(t) + f_j(t)) - f_i \right\|_2^2 \} ; \end{aligned}$$

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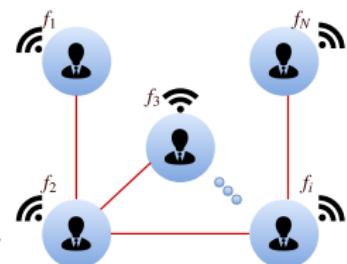
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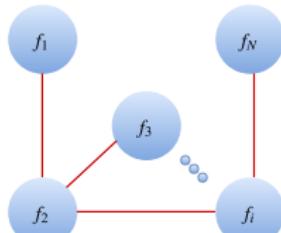
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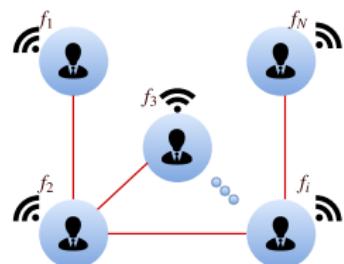
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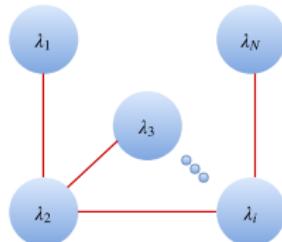
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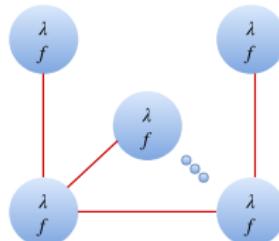
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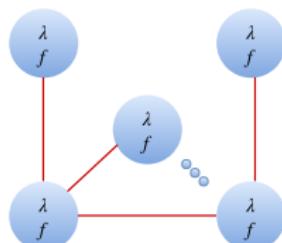
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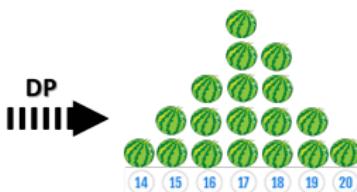


*How to make this procedure “private”?*

# Differential Privacy

- Obtain almost the same conclusion regardless of participation

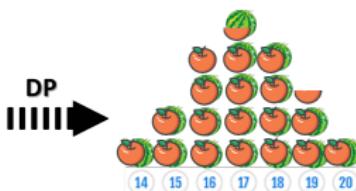
Student ID	Last Name	Initial	Age	Program
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ST348-247	Thompson	G.	18	Business
ST348-248	James	L.	23	Nursing
ST348-249	Peterson	M.	37	Science
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ST348-251	Smith	F.	26	Business
ST348-252	Nash	S.	22	Arts



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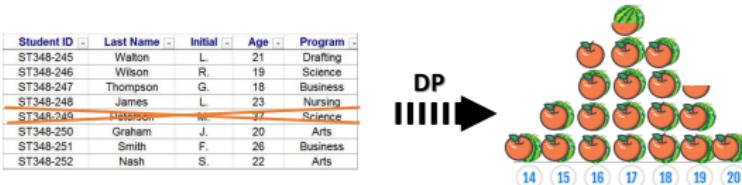
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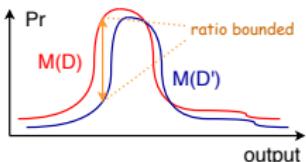
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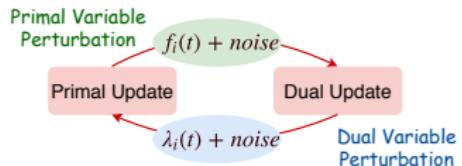
- A **randomized** algorithm  $M(\cdot)$  is  $\epsilon$ -differentially private if for **any** neighboring datasets  $D, D'$  and for **any** sets of possible outputs  $S \subseteq \text{range}(M)$ :

$$\frac{\Pr(M(D) \in S)}{\Pr(M(D') \in S)} \leq \exp(\epsilon)$$



# Existing work on differentially private ADMM

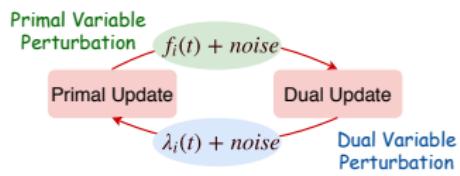
T. Zhang, et al. IEEE Trans. Inf. Forensic Secur. (2017)



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Issues:

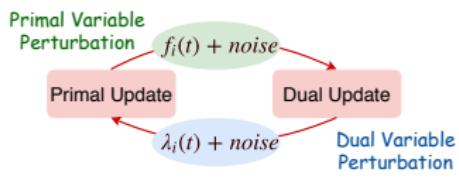


- Privacy loss only evaluated for a single node for one iteration.
- Privacy loss accumulates over iterations; hard to balance privacy and utility simply by summing up privacy losses.

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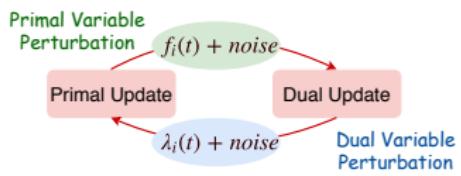
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- The total privacy loss of all nodes over the entire iterative process.
- M-ADMM to accommodate the private and varied penalty parameters for each node; increasing which can increase the algorithm's robustness and improve the privacy-utility tradeoff.

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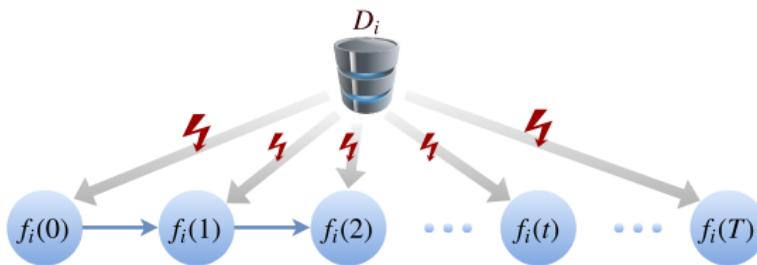
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*Can we improve more?*

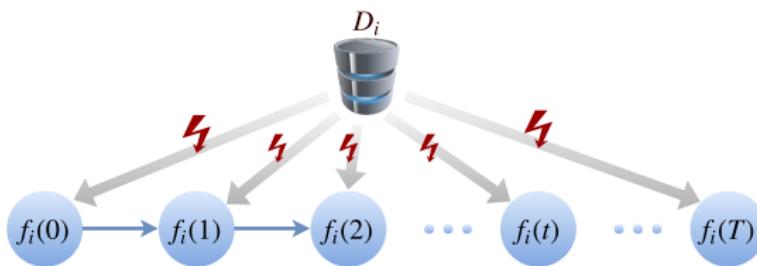
# Make information recyclable

Existing work: raw data is used in every update

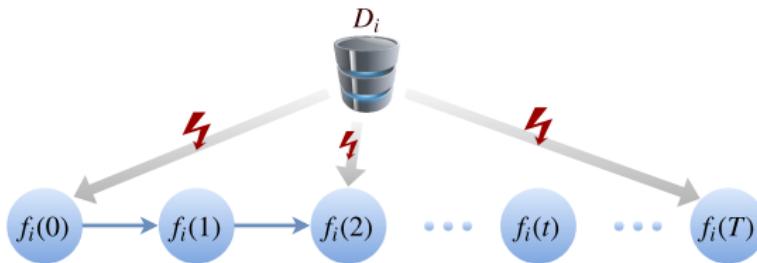


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Our idea: make some updates with the existing computation instead of the raw data



# Recycled ADMM

- Original primal updates:

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- Linearized approximation **only** in  $2k$ -th (even) updates:

$$\begin{aligned} O(f_i, D_i) &\approx O(f_i(2k-1), D_i) + \nabla O(f_i(2k-1), D_i)^T (f_i - f_i(2k-1)) \\ &\quad + \frac{\gamma}{2} \|f_i - f_i(2k-1)\|_2^2 \quad (\gamma \geq 0) \end{aligned}$$

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- Then the  $2k$ -th (even) primal update becomes:

$$\begin{aligned} f_i(2k) &= f_i(2k-1) - \frac{1}{2\eta V_i + \gamma} \{ \nabla O(f_i(2k-1), D_i) + 2\lambda_i(2k-1) \\ &\quad + \eta \sum_{j \in \mathcal{V}_i} (f_i(2k-1) - f_j(2k-1)) \} \end{aligned}$$

# Recycled ADMM

- Original primal updates:

$$f_i(t+1) = \underset{f_i}{\operatorname{argmin}} \{ O(f_i, D_i) + 2\lambda_i(t)^T f_i + \eta \sum_{j \in \mathcal{V}_i} \left\| \frac{1}{2}(f_i(t) + f_j(t)) - f_i \right\|_2^2 \}$$

- Linearized approximation **only** in  $2k$ -th (even) updates:

$$\begin{aligned} O(f_i, D_i) &\approx O(f_i(2k-1), D_i) + \nabla O(f_i(2k-1), D_i)^T (f_i - f_i(2k-1)) \\ &\quad + \frac{\gamma}{2} \|f_i - f_i(2k-1)\|_2^2 \quad (\gamma \geq 0) \end{aligned}$$

- Then the  $2k$ -th (even) primal update becomes:

$$\begin{aligned} f_i(2k) &= f_i(2k-1) - \frac{1}{2\eta V_i + \gamma} \{ \nabla O(f_i(2k-1), D_i) + 2\lambda_i(2k-1) \\ &\quad + \eta \sum_{j \in \mathcal{V}_i} (f_i(2k-1) - f_j(2k-1)) \} \end{aligned}$$

*The information is “recycled”!*

# Recycled ADMM

- Odd updates: conventional ADMM

$$\begin{aligned} f_i(2k-1) &= \underset{f_i}{\operatorname{argmin}} \{ O(f_i, D_i) + 2\lambda_i(2k-2)^T f_i \\ &\quad + \eta \sum_{j \in \mathcal{V}_i} \left\| \frac{1}{2}(f_i(2k-2) + f_j(2k-2)) - f_i \right\|_2^2 \} ; \end{aligned}$$

$$\lambda_i(2k-1) = \lambda_i(2k-2) + \frac{\eta}{2} \sum_{j \in \mathcal{V}_i} (f_i(2k-1) - f_j(2k-1)) ;$$

- Even updates: a variant of gradient descent

$$\begin{aligned} f_i(2k) &= f_i(2k-1) - \frac{1}{2\eta V_i + \gamma} \{ \nabla O(f_i(2k-1), D_i) + 2\lambda_i(2k-1) \\ &\quad + \eta \sum_{j \in \mathcal{V}_i} (f_i(2k-1) - f_j(2k-1)) \} ; \\ \lambda_i(2k) &= \lambda_i(2k-1) . \end{aligned}$$

# Differentially Private Recycled ADMM

- Odd updates: dual variable perturbation

$$f_i(2k-1) = \operatorname{argmin}_{f_i} \{ O(f_i, D_i) + (2\lambda_i(2k-2) + \epsilon_i(2k-1))^T f_i$$

$$+ \eta \sum_{j \in \mathcal{V}_i} \left\| \frac{1}{2} (f_i(2k-2) + f_j(2k-2)) - f_i \right\|_2^2 \}$$

$$\lambda_i(2k-1) = \lambda_i(2k-2) + \frac{\eta}{2} \sum_{j \in \mathcal{V}_i} (f_i(2k-1) - f_j(2k-1)) ;$$

- Even updates: sum operation over the existing stored information

$$f_i(2k) = f_i(2k-1) - \frac{1}{2\eta V_i + \gamma} \left\{ \eta \sum_{j \in \mathcal{V}_i} (f_i(2k-1) - f_j(2k-1)) \right.$$

$$\left. + 2\lambda_i(2k-1) + \underbrace{\epsilon_i(2k-1) + \nabla O(f_i(2k-1), D_i)}_{\text{the existing computation by KKT}} \right\} ;$$

$$\lambda_i(2k) = \lambda_i(2k-1) .$$

# Theoretical Results

## Convergence Analysis:

- A sufficient condition for the convergence of Recycled ADMM.

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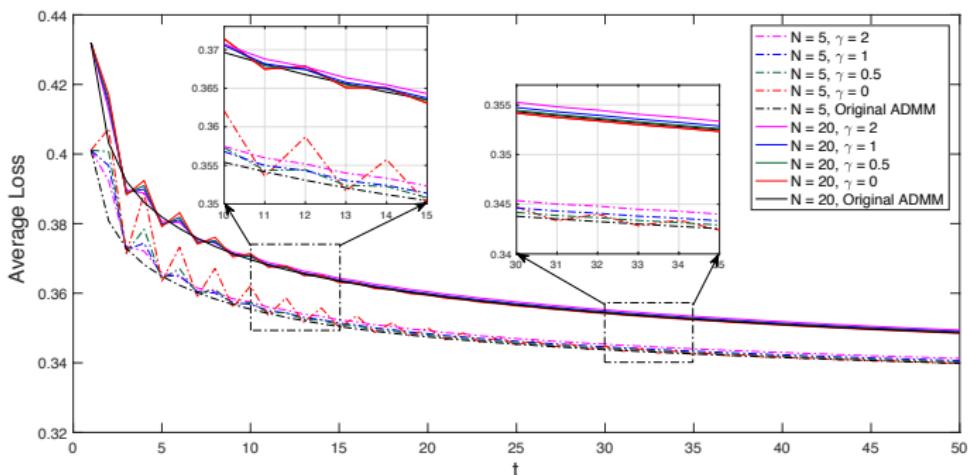
## Privacy Analysis:

- The **total privacy loss** during  $2K$  iterations.

$$\ln \frac{\Pr(\{\{f_i(t)\}_{i=1}^N\}_{t=0}^{2K} \in S | D_{all})}{\Pr(\{\{f_i(t)\}_{i=1}^N\}_{t=0}^{2K} \in S | \hat{D}_{all})} \leq \max_{i \in \mathcal{N}} \left\{ \sum_{k=1}^K \frac{2C}{B_i} \left( \frac{1.4c_1}{(\frac{\rho}{N} + 2\eta V_i)} + \alpha_i(k) \right) \right\}$$

# Numerical Results

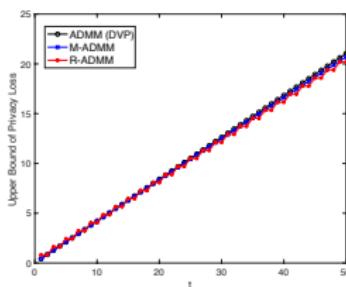
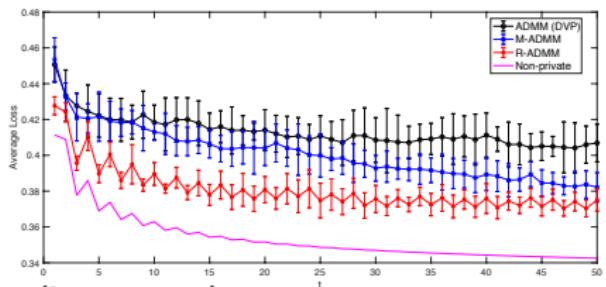
- Convergence of Recycled ADMM (non-private)



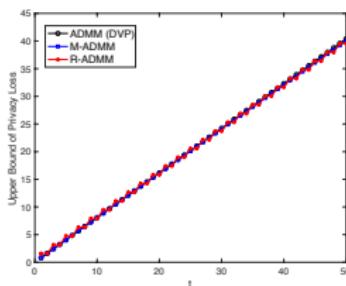
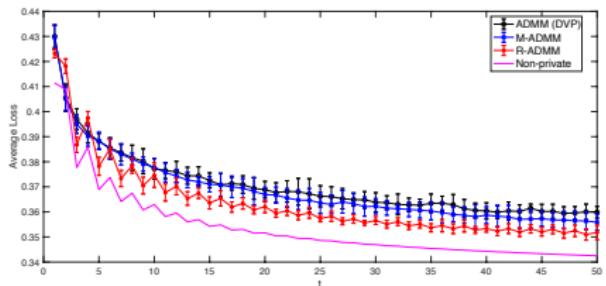
# Numerical Results

- Accuracy comparison under the same privacy guarantee

$\alpha_i = 2$  (more private)



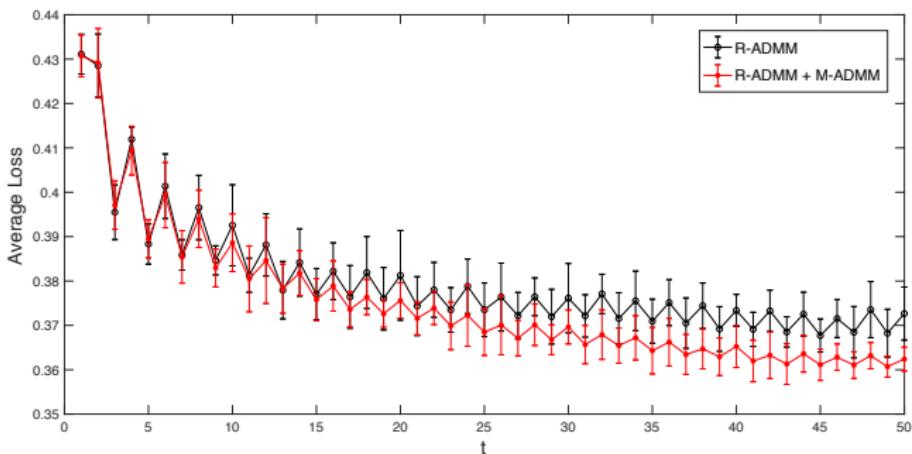
$\alpha_i = 4$  (less private)



- ADMM (DVP): T. Zhang, et al. IEEE Trans. Inf. Forensic Secur. (2017)
- M-ADMM: X. Zhang, et al. ICML (2018)

# Numerical Results

- Incorporate the idea from X. Zhang, et al. ICML (2018): Decrease the step-size (increase  $\eta$  and  $\gamma$ ) over iterations to stabilize the algorithm.



# Conclusions

- Recycled ADMM: improve the privacy-utility tradeoff significantly with less computation.
- Improvement is more significant with higher privacy requirement.
- Privacy-utility tradeoff can be further improved by controlling the step-size ( $\eta, \gamma$ ).

## Conclusions

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- Improvement is more significant with higher privacy requirement.
- Privacy-utility tradeoff can be further improved by controlling the step-size ( $\eta, \gamma$ ).

Thank you!